

MIXED LINEAR MODEL APPROACHES FOR ANALYZING GENETIC MODELS OF COMPLEX QUANTITATIVE TRAITS*

ZHU Jun(朱军)

(*Research Center of Biomathematics, Huajiachi Campus of Zhejiang University, Hangzhou 310029, China*)

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Abstract: New approaches based on general mixed linear models were presented for analyzing complex quantitative traits in animal models, seed models and QTL(quantitative trait locus) mapping models. Variances and covariances can be appropriately estimated by MINQUE(minimum norm quadratic unbiased estimation) approaches. Random genetic effects can be predicted without bias by LUP(linear unbiased prediction) or AUP(adjusted unbiased prediction) methods. Mixed-model based composite interval mapping (MCIM) methods are suitable for efficiently searching QTLs along the whole genome. Bayesian methods and Markov Chain Monte Carlo (MCMC) methods can be applied in analyzing parameters of random effects as well as their variances.

Key words: mixed model approaches, genetic models, estimation of variances and covariances, prediction of genetic effects, QTL mapping, Bayesian methods.

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INTRODUCTION

Many genetic models based on the approach of ANOVA (analysis of variance) were developed by Fisher(1925). Some of these models, e. g. NC design I and II(Comstock et al., 1952; Hallauer et al., 1981), diallel models (Yates, 1947; Griffing, 1956; Gardner and Eberhart, 1966), are still widely used by plant and animal breeders. But ANOVA approaches have some deficiencies in analyzing complex genetic models for quantitative traits. Many genetic models cannot be appropriately analyzed by the ANOVA approach if they have more complicated effects other than additive and dominance effects, e. g. Eisen's animal model with sex-linkage and maternal effects (Eisen et al., 1966) and a bio-model including maternal and paternal effects (Cockerham and Weir, 1977).

In the 1970's, statisticians developed some methods for analyzing mixed linear models which can be applied in quantitative genetics. Mixed linear model approaches can overcome the shortcomings of ANOVA methods for handling unbalanced data and complicated models. Development of mixed linear model approaches and their application in quantitative genetics will create

enormous challenges for quantitative geneticists in dealing with complicated genetic problems.

In the present paper we will review some of our recent works in extending the mixed linear model approaches and constructing complicated genetic models for analyzing complex quantitative traits. Methods recently developed for mixed linear models and their applications will be given to show the ways for solving the real complicated problems in quantitative genetics.

MIXED LINEAR MODEL APPROACHES

General mixed linear models

Many genetic models with biological meanings for different generations are complicated and have no integer coefficients or even correlated effects. Parameters in these genetic models are not manageable by traditional ANOVA methods, but can be analyzed by mixed linear model approaches.

Most genetic models can be expressed by a general form of the mixed linear model,

$$y = X_1 b_1 + X_2 b_2 + \dots + X_n b_n + U_1 e_1 + U_2 e_2 + \dots + U_{m-1} e_{m-1} + e_m$$

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$$= \mathbf{Xb} + \sum_{u=1}^m \mathbf{U}_u \mathbf{e}_u \sim \mathcal{N}(\mathbf{Xb}, \mathbf{V}) \quad (1)$$

where \mathbf{y} is the vector ($n \times 1$) of phenotype value with mean \mathbf{Xb} and variance \mathbf{V} ; \mathbf{b} is the vector ($p \times 1$) of fixed effects; \mathbf{X} is the known incidence matrix ($n \times p$) relating to the fixed effects; \mathbf{e}_u ($u = 1, 2, \dots, m-1$) is the vector ($q_u \times 1$) of the u -th random factor, $\mathbf{e}_u \sim (\mathbf{O}, \sigma_u^2 \mathbf{R}_u)$, \mathbf{R}_u is a constant matrix describing the relationship of \mathbf{e}_u ; \mathbf{U}_u is the known coefficient matrix relating to the random vector \mathbf{e}_u , \mathbf{e}_m is the vector ($n \times 1$) of the residual random effects with $\mathbf{e}_m \sim (\mathbf{O}, \sigma_m^2 \mathbf{I})$ and $\mathbf{R}_m = \mathbf{I}$.

If random factors are independent with cov ($\mathbf{e}_u, \mathbf{e}_v^T$) = \mathbf{O} , $\mathbf{V} = \sum_{u=1}^m \sigma_u^2 \mathbf{V}_u$ with $\mathbf{V}_u = \mathbf{U}_u \mathbf{R}_u \mathbf{U}_u^T$ ($u = 1, 2, \dots, m-1$) and $\mathbf{V}_m = \mathbf{I}$. When random effects of \mathbf{e}_u are also independent ($\mathbf{R}_u = \mathbf{I}$), then $\mathbf{V}_u = \mathbf{U}_u \mathbf{U}_u^T$.

Variance and covariance estimation

The variances in model (1) can be analyzed by mixed linear model approaches such as maximum likelihood (ML) method (Hartley and Rao, 1967), restricted maximum likelihood (REML) method (Patterson and Thompson, 1971), or minimum norm quadratic unbiased estimation (MINQUE) method (Rao, 1971).

When random factors are independent, estimated variance components can be obtained by the methods of ML in (2), REML in (3), or MINQUE in (4). ML estimates of variances can be calculated by numerically solving the following normal equations

$$[\text{tr}(\hat{\mathbf{V}}_{[h]}^{-1} \mathbf{V}_u \hat{\mathbf{V}}_{[h]}^{-1}) \mathbf{V}_v \mathbf{I} \hat{\sigma}_{u[h+1]}^2] = [\mathbf{y}^T \hat{\mathbf{Q}}_{[h]} \mathbf{V}_u \hat{\mathbf{Q}}_{[h]} \mathbf{y}] \quad (2)$$

where

$$\hat{\mathbf{Q}}_{[h]} = \hat{\mathbf{V}}_{[h]}^{-1} - \hat{\mathbf{V}}_{[h]}^{-1} \mathbf{X} (\mathbf{X}^T \hat{\mathbf{V}}_{[h]}^{-1} \mathbf{X})^+ \mathbf{X}^T \hat{\mathbf{V}}_{[h]}^{-1}$$

$$\hat{\mathbf{V}}_{[h]} = \sum_n \hat{\sigma}_{u[h]}^2 \mathbf{V}_u = \sum \hat{\sigma}_{u[h]}^2 \mathbf{U}_u \mathbf{R}_u \mathbf{U}_u^T$$

$\hat{\sigma}_{u[h]}^2$ is the estimate of σ_u^2 by the h -th iteration.

Estimated variances obtained by the ML method tend to be influenced by the fixed effects, so ML is rarely used. The REML estimation

method can overcome the influence of the fixed effects. The normal equations for obtaining REML estimates of variances are very similar to equation (2), except that $\hat{\mathbf{V}}_{[h]}$ in the left-hand side of equation (2) is replaced by $\hat{\mathbf{Q}}_{[h]}$,

$$[\text{tr}(\hat{\mathbf{Q}}_{[h]} \mathbf{V}_u \hat{\mathbf{Q}}_{[h]} \mathbf{V}_v \mathbf{I} \hat{\sigma}_{u[h+1]}^2)] = [\mathbf{y}^T \hat{\mathbf{Q}}_{[h]} \mathbf{V}_u \hat{\mathbf{Q}}_{[h]} \mathbf{y}] \quad (3)$$

The MINQUE method does not need the assumption of normal distribution for observed data, and can give estimated variances without iteration. The MINQUE equations for estimating variance components are

$$[\text{tr}(\mathbf{Q}_\alpha \mathbf{V}_u \mathbf{Q}_\alpha \mathbf{V}_v \mathbf{I} \hat{\sigma}_u^2)] = [\mathbf{y}^T \mathbf{Q}_\alpha \mathbf{V}_u \mathbf{Q}_\alpha \mathbf{y}_2] \quad (4)$$

where

$$\mathbf{Q}_\alpha = \mathbf{V}_\alpha^{-1} - \mathbf{V}_\alpha^{-1} \mathbf{X} (\mathbf{X}^T \mathbf{V}_\alpha^{-1} \mathbf{X})^+ \mathbf{X}^T \mathbf{V}_\alpha^{-1}$$

$$\mathbf{V}_\alpha = \sum_u \alpha_u \mathbf{V}_u = \sum_u \alpha_u \mathbf{U}_u \mathbf{R}_u \mathbf{U}_u^T$$

Covariance components $\sigma_{u/u}$ between two traits (\mathbf{y}_1 and \mathbf{y}_2) can also be easily estimated without bias by solving the following equations (Zhu and Weir, 1996),

$$[\text{tr}(\mathbf{Q}_\alpha \mathbf{V}_u \mathbf{Q}_\alpha \mathbf{V}_v \mathbf{I} \hat{\sigma}_{u/u})] = [\mathbf{y}_1^T \mathbf{Q}_\alpha \mathbf{V}_u \mathbf{Q}_\alpha \mathbf{y}_2] \quad (5)$$

The MINQUE method uses the prior values α_u that may be chosen from prior experiments, from iterations or theoretical considerations. MINQUE(1) as a MINQUE method with $\alpha_u = 1$ can be employed for estimating variance components when random factors are independent.

For certain genetic models, some of the random factors are correlated. Variance matrix \mathbf{V} consists of variance components (σ_u^2) for random factors and also covariance components ($\sigma_{u,v}$) between correlated random factors. Zhu and Weir (1994a, 1994b) proposed genetic models for diploid seed and triploid endosperm, which can be written by a mixed linear model,

$$\begin{aligned} \mathbf{y} &= \mathbf{Xb} + \mathbf{U}_A \mathbf{e}_A + \mathbf{U}_D \mathbf{e}_D + \mathbf{U}_C \mathbf{e}_C + \mathbf{U}_{Am} \mathbf{e}_{Am} \\ &\quad + \mathbf{U}_{Dm} \mathbf{e}_{Dm} + \mathbf{U}_B \mathbf{e}_B + \mathbf{e}_\epsilon \\ &= \mathbf{Xb} + \sum_u^7 \mathbf{U}_u \mathbf{e}_u \end{aligned} \quad (6)$$

with variance matrix

$$\begin{aligned} \mathbf{V} &= \sigma_A^2 \mathbf{V}_1 + \sigma_D^2 \mathbf{V}_2 + \sigma_C^2 \mathbf{V}_3 + \sigma_{Am}^2 \mathbf{V}_4 + \sigma_{Dm}^2 \mathbf{V}_5 \\ &\quad + \sigma_B^2 \mathbf{V}_6 + \sigma_{A.Am} \mathbf{V}_7 + \sigma_{D.Dm} \mathbf{V}_8 + \sigma_\epsilon^2 \mathbf{V}_9 \end{aligned}$$

$$= \sum_{u=1}^9 \theta_u \mathbf{V}_u$$

where $\mathbf{V}_u = \mathbf{U}_u \mathbf{U}_u^T$ ($u = 1, 2, \dots, 6$), $\mathbf{V}_7 = (\mathbf{U}_1 \mathbf{U}_4^T + \mathbf{U}_4 \mathbf{U}_1^T)$, $\mathbf{V}_8 = (\mathbf{U}_2 \mathbf{U}_5^T + \mathbf{U}_5 \mathbf{U}_2^T)$, $\mathbf{V}_9 = \mathbf{I}$.

MINQUE(0/1) was suggested by Zhu and Weir (1994a) for unbiased estimation of variances and covariances for one traits and covariances between two traits. MINQUE(0/1) procedure is a MINQUE method setting 0 for all the prior covariances ($\alpha_{u,v}$) and 1 for all the prior variances (α_u). Variances and covariances for one trait ($\mathbf{y}_1 = \mathbf{y}_2$), and covariances between two traits ($\mathbf{y}_1 \neq \mathbf{y}_2$) can be estimated by the following MINQUE(0/1) equations,

$$\begin{aligned} & [\text{tr}(\mathbf{Q}_{(0/1)} \mathbf{V}_u \mathbf{Q}_{(0/1)} \mathbf{V}_v) \mathbf{I} \hat{\theta}_{u/v}] \\ & = [\mathbf{y}_1^T \mathbf{Q}_{(0/1)} \mathbf{V}_u \mathbf{Q}_{(0/1)} \mathbf{y}_2] \end{aligned} \quad (7)$$

where

$$\begin{aligned} \mathbf{Q}_{(0/1)} &= \mathbf{V}_{(0/1)}^{-1} - \mathbf{V}_{(0/1)}^{-1} \mathbf{X} (\mathbf{X}^T \mathbf{V}_{(0/1)}^{-1} \mathbf{X})^{-1} \\ &\cdot \mathbf{X}^T \mathbf{V}_{(0/1)}^{-1} \\ \mathbf{V}_{(0/1)} &= \sum_{u=1}^6 \mathbf{U}_u \mathbf{U}_u^T + \mathbf{I} \end{aligned}$$

Monte Carlo simulations showed that both variances and covariances of seed traits can be unbiasedly estimated by the MINQUE(0/1) procedure (Zhu and Weir, 1994a, 1994b).

In plant breeding, breeders usually want to improve seed quality traits while still keeping the genetic merit of yield traits. Therefore understanding the genetic relationship between seed quality traits and plant yield traits is of importance. Seed models and plant models have unequal design matrices. Zhu (1993b) developed a new method for estimating genetic covariance components between seed traits (\mathbf{y}_s) and plant traits (\mathbf{y}_p). For seed model (6), the correspondent plants bearing the seeds will have the following mixed linear model,

$$\begin{aligned} \mathbf{y}_{(P)} &= \mathbf{X} \mathbf{b}_{(P)} + \mathbf{U}_C \mathbf{e}_{\alpha(P)} + \mathbf{U}_{Am} \mathbf{e}_{Am(P)} \\ &+ \mathbf{U}_{Dm} \mathbf{e}_{Dm(P)} + \mathbf{U}_B \mathbf{e}_{\beta(P)} + \mathbf{e}_{\varepsilon(P)} \\ &= \mathbf{X} \mathbf{b}_{(P)} + \sum_u^5 \mathbf{U}_u \mathbf{e}_{u(P)} \end{aligned}$$

There are covariances between random factors of seed traits and those of plant traits: $\sigma_{A/Am}$ = covariance between seed direct additive effects and

plant additive effects, $\sigma_{D/Dm}$ = covariance between seed direct dominance effects and plant dominance effects, $\sigma_{C/C}$ = covariance between seed cytoplasm effects and plant cytoplasm effects, $\sigma_{Am/Am}$ = covariance between seed maternal additive effects and plant additive effects, $\sigma_{Dm/Dm}$ = covariance between seed maternal dominance effects and plant dominance effects, $\sigma_{B/B}$ = covariance between seed block effects and plant block effects, $\sigma_{\varepsilon/\varepsilon}$ = covariance between seed residual effects and plant residual effects.

If we define $\mathbf{F}_1 = (\mathbf{U}_A \mathbf{U}_{Am}^T + \mathbf{U}_{Am} \mathbf{U}_A^T)$, $\mathbf{F}_2 = (\mathbf{U}_D \mathbf{U}_{Dm}^T + \mathbf{U}_{Dm} \mathbf{U}_D^T)$, $\mathbf{F}_3 = (2\mathbf{U}_C \mathbf{U}_C^T)$, $\mathbf{F}_4 = (2\mathbf{U}_{Am} \mathbf{U}_{Am}^T)$, $\mathbf{F}_5 = (2\mathbf{U}_{Dm} \mathbf{U}_{Dm}^T)$, $\mathbf{F}_6 = (2\mathbf{U}_B \mathbf{U}_B^T)$, and $\mathbf{F}_7 = 2\mathbf{I}$, covariance components between seed trait and plant trait can then be estimated by the following equations:

$$\begin{aligned} & [\text{tr}(\mathbf{Q}_{(0/1)} \mathbf{F}_u \mathbf{Q}_{(0/1)} \mathbf{F}_v) \mathbf{I} \hat{\sigma}_{u/v}] \\ & = [2\mathbf{y}_s^T \mathbf{Q}_{(0/1)} \mathbf{F}_u \mathbf{Q}_{(0/1)} \mathbf{y}_p] \end{aligned} \quad (8)$$

where

$$\begin{aligned} \mathbf{Q}_{(0/1)} &= \mathbf{V}_{(0/1)}^{-1} - \mathbf{V}_{(0/1)}^{-1} \mathbf{X} (\mathbf{X}^T \mathbf{V}_{(0/1)}^{-1} \mathbf{X})^{-1} \\ &\cdot \mathbf{X}^T \mathbf{V}_{(0/1)}^{-1} \\ \mathbf{V}_{(0/1)} &= \mathbf{X} \mathbf{U}_C \mathbf{U}_C^T + \mathbf{U}_{Am} \mathbf{U}_{Am}^T + \mathbf{U}_{Dm} \mathbf{U}_{Dm}^T \\ &+ \mathbf{U}_B \mathbf{U}_B^T + \mathbf{I} \end{aligned}$$

For time-dependable traits, the phenotype data observed at time t ($t = 1, 2, \dots$) has the following mixed linear model,

$$\begin{aligned} \mathbf{y}_{(t)} &= \mathbf{X} \mathbf{b}_{(t)} + \sum_{u=1}^m \mathbf{U}_u \mathbf{e}_{u(t)} \\ &\sim \mathcal{N}(\mathbf{X} \mathbf{b}_{(t)}, \mathbf{V}_{(t)}) = \sum_{u=1}^m \sigma_{u(t)}^2 \mathbf{U}_u \mathbf{R}_u \mathbf{U}_u^T \end{aligned}$$

Given the observed phenotype vector $\mathbf{y}_{(t-1)}$ measured at time ($t-1$), the conditional random variables of $\mathbf{y}_{(t)} | \mathbf{y}_{(t-1)}$ at time t have conditional distribution,

$$\begin{aligned} \mathbf{y}_{(t)} | \mathbf{y}_{(t-1)} &= \mathbf{X} \mathbf{b}_{(t|t-1)} + \sum_{u=1}^m \mathbf{U}_u \mathbf{e}_{u(t|t-1)} \\ &\sim \mathcal{N}(\mathbf{X} \mathbf{b}_{(t|t-1)}, \mathbf{V}_{(t|t-1)}) \\ &= \sum_{u=1}^m \sigma_{u(t|t-1)}^2 \mathbf{U}_u \mathbf{R}_u \mathbf{U}_u^T \end{aligned} \quad (9)$$

Since conditional $\mathbf{y}_{(t)} | \mathbf{y}_{(t-1)}$ is independent of $\mathbf{y}_{(t-1)}$, conditional random effects $\mathbf{e}_{(t|t-1)}$ and

conditional variance components $\sigma_{\epsilon(t|t-1)}^2$ contain extra variation not explainable by the accumulated effects from the initial time to time $t-1$. Zhu (1995) proposed a mixed model approach for analyzing conditional variance components and conditional random effects, which had been used in developmental quantitative genetic analysis (Atchley and Zhu, 1997; Yan et al., 1998).

When phenotypic vector \mathbf{y} has large size and multivariate normal distribution, variance estimates will have asymptotic multivariate normal distribution,

$$[\hat{\sigma}_u^2] \sim N([\sigma_u^2] 2\mathbf{H}^{-1}) \quad (10)$$

where $\mathbf{H} = [\text{tr}(\mathbf{V}^{-1} \mathbf{V}_u \mathbf{V}^{-1} \mathbf{V}_v)]^{-1}$ for ML estimates (Searle, 1970), or $\mathbf{H} = [\text{tr}(\mathbf{QV}_u \mathbf{QV}_v)]^{-1}$ for REML estimates (Searle, 1970) and MINQUE estimates (Rao and Kleffe, 1988).

Hypothesis test for linear combination of variances can be conducted by a χ^2 test. For null hypothesis $H_0: \sum_{u=1}^m c_u \sigma_u^2 = \rho$ vs. alternative hypothesis $H_1: \sum_{u=1}^m c_u \sigma_u^2 \neq \rho$, the statistic χ_{cal}^2 will asymptotically have χ^2 distribution with 1 degree of freedom when H_0 is true,

$$\chi_{\text{cal}}^2 = \frac{(\sum_{u=1}^m c_u \hat{\sigma}_u^2 - \rho)^2}{2(\sum_{u=1}^m c_u^2 \hat{\mathbf{H}}_{uu}^{-1} + 2 \sum_{u=1}^{m-1} \sum_{v>u}^m c_u^2 c_v^2 \hat{\mathbf{H}}_{uv}^{-1})} \quad (11)$$

$H_0 \quad \chi_{(df=1)}^2$

If $\chi_{\text{cal}}^2 > \chi_{(df=1)}^2$, H_0 will be rejected and H_1 be accepted, otherwise H_0 is not rejectable.

Zhu and Weir (1994a, 1996) suggested obtaining estimates and their standard errors by resampling genetic entries or experimental blocks with the Jackknife method (Miller, 1974).

If $\hat{\theta}$ is an estimate of a genetic parameter from a sample of K entries, and $\hat{\theta}_k$ ($k = 1, 2, \dots, K$) is the estimate resulting when entry k is omitted, then the Jackknife estimate $\hat{\theta}_J$ and its sampling variance $\text{var}(\hat{\theta}_J)$ are

$$\hat{\theta}_J = K\hat{\theta} - (K-1)\bar{\hat{\theta}}$$

$$\text{var}(\hat{\theta}_J) = \frac{K-1}{K} \sum_{k=1}^K (\hat{\theta}_k - \bar{\hat{\theta}})^2$$

where $\bar{\hat{\theta}} = \frac{1}{K} \sum_{k=1}^K \hat{\theta}_k$. If K is not large, $(\hat{\theta}_J - \theta) / \sqrt{\text{var}(\hat{\theta}_J)}$ is approximately distributed as a t -distribution with $(K-1)$ degrees freedom under the null hypothesis H_0 .

Monte Carlo simulation showed that statistical test for variances by χ^2 test in equation (11) is much more conservative than that by a t -test with the Jackknife procedure (Zhu, 1989).

Random effects prediction

Except for the residual effects \mathbf{e}_m , random effects in mixed linear model (1) can be predicted by the best linear unbiased prediction (BLUP) method (Henderson, 1963). Henderson (1988) proposed a general approach which can result in both unbiased estimation for fixed effects and unbiased prediction for random effects, without calculating the inverse of \mathbf{V} . For model (1), the estimation and prediction can be obtained by solving the following equations,

$$\begin{bmatrix} \mathbf{X}^T \mathbf{R}_m^{-1} \mathbf{X} & \mathbf{X}^T \mathbf{R}_m^{-1} \mathbf{U}_1 & \mathbf{X}^T \mathbf{R}_m^{-1} \mathbf{U}_2 & \dots \\ \mathbf{U}_1^T \mathbf{R}_m^{-1} \mathbf{X} & \mathbf{U}_1^T \mathbf{R}_m^{-1} + \mathbf{R}_1^{-1} / \sigma_1^2 & \mathbf{U}_1^T \mathbf{R}_m^{-1} \mathbf{U}_2 & \dots \\ \mathbf{U}_2^T \mathbf{R}_m^{-1} \mathbf{X} & \mathbf{U}_2^T \mathbf{R}_m^{-1} \mathbf{Z}_1 & \mathbf{U}_2^T \mathbf{R}_m^{-1} \mathbf{U}_2 + \mathbf{R}_2^{-1} / \sigma_2^2 & \dots \end{bmatrix} \cdot \begin{bmatrix} \hat{\mathbf{b}} \\ \hat{\mathbf{e}}_1 \\ \hat{\mathbf{e}}_2 \end{bmatrix} = \begin{bmatrix} \mathbf{X}^T \mathbf{R}_m^{-1} \mathbf{y} \\ \mathbf{U}_1^T \mathbf{R}_m^{-1} \mathbf{y} \\ \mathbf{U}_2^T \mathbf{R}_m^{-1} \mathbf{y} \end{bmatrix} \quad (12)$$

Normal equations (12) can be expressed simply as $\mathbf{WB}\beta = \mathbf{d}$.

Since the solution of equations (12) requires the unknown variances, Eq. (12)'s estimates still depend on the calculation of $\hat{\mathbf{V}}^{-1}$ by the REML method.

If fixed effects and random effects of some factors are not of interest, we can obtain BLUP for specific random effects \mathbf{e}_u ($u = 1, 2, \dots, m-1$) (Henderson, 1963),

$$\hat{\mathbf{e}}_{u(\sigma^2)} = \sigma_u^2 \mathbf{R}_u \mathbf{U}_u^T \mathbf{V}^{-1} (\mathbf{y} - \mathbf{X}\hat{\mathbf{b}})$$

$$= \sigma_u^2 \mathbf{R}_u \mathbf{U}_u^T \mathbf{Qy} \quad (13)$$

Since the true variances are always unknown in practice, estimated variances are usually used in prediction:

$$\hat{\mathbf{e}}_{u(\hat{\sigma}^2)} = \hat{\sigma}_u^2 \mathbf{R}_u \mathbf{U}_u^T \hat{\mathbf{Qy}} \quad (14)$$

With such prediction by using estimates, only a

so-called BLUP which may have lost linearity and unbiasedness, is obtainable.

Instead of using parameters (13) or their estimates (14) for predicting random effects, Zhu and Weir (1996) suggested choosing prior values α_u as in the case of the MINQUE method,

$$\hat{e}_{u(\alpha)} = \alpha_u \mathbf{R}_u \mathbf{U}_u^T \mathbf{Q}_\alpha \mathbf{y} \quad (15)$$

If the choice of prior value is not based on the observed data, the predictor \hat{e}_u is a linear unbiased prediction (LUP) for random vector \mathbf{e}_u .

Monte Carlo simulations revealed that both BLUP and LUP will give prediction with unbiased mean but under-estimated variance ($E(\hat{\mathbf{e}}^T \hat{\mathbf{e}}/df) < \sigma^2$) for random variables (Zhu and Weir, 1996). In order to solve this problem, a method of adjusted unbiased prediction (AUP) was suggested for predicting random variables (Zhu, 1993a; Zhu and Weir, 1996),

$$\hat{e}_{u(\alpha)}^A = \kappa_u (\alpha_u \mathbf{R}_u \mathbf{U}_u^T \mathbf{Q}_\alpha \mathbf{y}) \quad (16)$$

where $\kappa_u = \sqrt{(q_u - 1) \delta_u^2 / (\alpha_u^2 \mathbf{y}^T \mathbf{Q}_\alpha \mathbf{V}_u \mathbf{Q}_\alpha \mathbf{y})}$ is an adjusted coefficient to insure $\hat{e}_{u(\alpha)}^A \hat{e}_{u(\alpha)}^A / (q_u - 1) = \delta_u^2$, and set $\delta_u^2 = 0$ when $\hat{\sigma}_u^2 < 0$.

Monte Carlo simulations proved that AUP gives unbiased mean and variance for predicted effects (Zhu and Weir, 1996).

For mixed linear models with correlated random variables $\text{cov}(\mathbf{e}_u, \mathbf{e}_v^T) = \sigma_{u,v} \mathbf{R}_{u,v}$, the BLUP for random effects \mathbf{e}_u is given by,

$$\hat{e}_{u(\theta)} = (\sigma_u^2 \mathbf{R}_u \mathbf{U}_u^T + \sigma_{u,v} \mathbf{R}_{u,v} \mathbf{U}_v^T) \mathbf{Q} \mathbf{y} \quad (17)$$

When MINQUE(0/1) is used for estimating variances and covariances for seed traits (Zhu and Weir, 1994a), LUP can be used for predicting random genetic effects \mathbf{e}_u ($u = 1, 2, \dots, m - 1$).

$$\hat{e}_{u(0/1)} = \mathbf{R}_u \mathbf{U}_u^T \mathbf{Q}_{(0/1)} \mathbf{y} \quad (18)$$

And AUP is obtainable by

$$\hat{e}_{u(0/1)}^A = \kappa \mathbf{R}_u \mathbf{U}_u^T \mathbf{Q}_{(0/1)} \mathbf{y} \quad (19)$$

where $\kappa = \sqrt{(q_u - 1) \delta_u^2 / (\mathbf{y}^T \mathbf{Q}_{(0/1)} \mathbf{V}_u \mathbf{Q}_{(0/1)} \mathbf{y})}$.

When random effects are predicted by BLUP or LUP, the sampling variances for predicted effects can be calculated by

$$\begin{aligned} \text{va}(\hat{e}_{u(\sigma^2)}) &= \text{va}(\sigma_u^2 \mathbf{R}_u \mathbf{U}_u^T \mathbf{Q} \mathbf{y}) \\ &= (\sigma_u^2)^2 \mathbf{R}_u \mathbf{U}_u^T \mathbf{Q} \text{va}(\mathbf{y}) \mathbf{Q} \mathbf{U}_u \mathbf{R}_u \end{aligned}$$

$$\begin{aligned} &= (\sigma_u^2)^2 \mathbf{R}_u \mathbf{U}_u^T \mathbf{Q} \mathbf{V} \mathbf{Q} \mathbf{U}_u \mathbf{R}_u \\ &= (\sigma_u^2)^2 \mathbf{R}_u \mathbf{U}_u^T \mathbf{Q} \mathbf{U}_u \mathbf{R}_u \quad (20) \end{aligned}$$

for BLUP, and

$$\begin{aligned} \text{va}(\hat{e}_{u(\alpha)}) &= \text{va}(\alpha_u \mathbf{R}_u \mathbf{U}_u^T \mathbf{Q}_\alpha \mathbf{y}) \\ &= (\alpha_u)^2 \mathbf{R}_u \mathbf{U}_u^T \mathbf{Q}_\alpha \text{va}(\mathbf{y}) \mathbf{Q}_\alpha \mathbf{U}_u \mathbf{R}_u \\ &= \alpha_u^2 \mathbf{R}_u \mathbf{U}_u^T \mathbf{Q}_\alpha \mathbf{V} \mathbf{Q}_\alpha \mathbf{U}_u \mathbf{R}_u \quad (21) \end{aligned}$$

for LUP.

Hypothesis test for linear combination of genetic effects can be conducted by a χ^2 test in the same way as the variance test. But Zhu and Weir (1994a, 1996) suggested use of the Jackknife resampling technique in conducting a t -test for predicted genetic effects because it is more powerful for detecting non-zero parameters.

QTL mapping approaches

For mapping quantitative trait loci (QTLs) of plants, putative QTL within two flanking markers M_{i-} and M_{i+} is searched along the whole genome. The markers linked to other QTLs are often included as fixed effects in a regression model for controlling background noise (Jansen, 1993; Zeng, 1994). For mapping QTLs of animal populations, QTLs effects are often treated as random effects, which will fit the framework of mixed linear models (Grignola et al., 1997; Wang et al., 1998). The QTL effects for these animal models are predicted by Henderson's BLUP approach as in equation (12).

An approach of mixed-model-based composite interval mapping (MCIM) (Zhu, 1998; 1999; Zhu and Weir, 1998; Wang et al., 1999), by which the marker effects are treated as random effects, can be constructed for handling QTL \times environment interaction or other complicated effects. If the MCIM approach is used, QTL mapping models can all be expressed in the general mixed linear model (1). The likelihood function (L) for the parameters of fixed effects \mathbf{b} and variance components [σ_u^2] is

$$\begin{aligned} L(\mathbf{b}, \mathbf{V}) &= (2\pi)^{-\frac{n}{2}} |\mathbf{V}|^{-\frac{1}{2}} \exp\left[-\frac{1}{2}(\mathbf{y} \right. \\ &\quad \left. - \mathbf{X}\mathbf{b})^T \mathbf{V}^{-1}(\mathbf{y} - \mathbf{X}\mathbf{b})\right] \quad (22) \end{aligned}$$

with the log of the likelihood function (1) as

$$\ln L(\mathbf{b}, \mathbf{V}) = -\frac{n}{2} \ln(2\pi) - \frac{1}{2} \ln |\mathbf{V}|$$

$$-\frac{1}{2}(\mathbf{y} - \mathbf{X}\mathbf{b})^T \mathbf{V}^{-1}(\mathbf{y} - \mathbf{X}\mathbf{b}) \quad (23)$$

If variance components of the model are known, the maximum likelihood estimates of QTL effects in \mathbf{b} can be obtained by the maximum likelihood estimation,

$$\hat{\mathbf{b}} = (\mathbf{X}^T \mathbf{V}^{-1} \mathbf{X})^{-1} \mathbf{X}^T \mathbf{V}^{-1} \mathbf{y} \quad (24)$$

with sampling variance matrix

$$\text{va}(\hat{\mathbf{b}}) = (\mathbf{X}^T \mathbf{V}^{-1} \mathbf{X})^{-1}.$$

We can search QTL within two flanking markers M_{i-} and M_{i+} for the whole genome by setting a prior value for recombination fraction $r_{M_{i-}Q}$ between marker and locus Q . For each prior value $\hat{r}_{M_{i-}Q}$, the likelihood ratio statistic (LR) can be calculated by

$$LR = 2l_1(\hat{\mathbf{b}}, \hat{\mathbf{V}}, \hat{r}_{M_{i-}Q}) - 2l_0(\hat{\mathbf{b}}, \hat{\mathbf{V}}, \hat{r}_{M_{i-}Q} = 0.5) \quad (25)$$

where variance components in \mathbf{V} can be replaced by their unbiased estimates,

$$\hat{\mathbf{V}} = \sum_u \hat{\sigma}_u^2 \mathbf{U}_u \mathbf{R}_u \mathbf{U}_u$$

The likelihood ratio statistic can also be used for testing the null hypothesis $H_0 : r_{M_{i-}Q} = 0.5$ vs. the alternative hypothesis $H_1 : r_{M_{i-}Q} < 0.5$. LR approximately has χ^2 distribution.

When the null presentation of no QTL within two flanking markers M_{i-} and M_{i+} is rejected, $\hat{r}_{M_{i-}Q}$ infers the position of the QTL while $\hat{\mathbf{b}}$ gives the estimates of additive and dominance effects of this QTL. Hypothesis for additive and dominance effects can be conducted by a t -test in a general way for

$$H_0 : \mathbf{c}'\mathbf{b} = m \text{ vs. } H_1 : \mathbf{c}'\mathbf{b} \neq m$$

If the statistic $|\mathbf{c}'(\hat{\mathbf{b}} - \mathbf{b})| \sqrt{\mathbf{c}'(\hat{\mathbf{X}}'\hat{\mathbf{V}}^{-1}\hat{\mathbf{X}})\mathbf{c}} > z_{(\alpha/2)}$, the null hypothesis is then rejected.

Bayesian analysis

Bayesian methods and Markov Chain Monte Carlo (MCMC) methods were recently applied in QTL mapping (Bink et al., 1998). The conditional distribution for generating the data is:

$$\mathbf{y} | \mathbf{b}, \mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_{m-1}, \sigma_m^2 \sim N\left(\mathbf{X}\mathbf{b} + \sum_{u=1}^{m-1} \mathbf{U}_u \mathbf{e}_u, \sigma_m^2 \mathbf{I}\right) \quad (26)$$

The prior distributions for the unknowns in the model can be assigned for \mathbf{b}, \mathbf{e}_u ($u = 1, 2, \dots, m-1$) and σ_m^2 (Wang et al., 1994).

$$\begin{aligned} \text{Let } \boldsymbol{\beta}^T &= [\mathbf{b}^T, \mathbf{e}_1^T, \mathbf{e}_2^T, \dots, \mathbf{e}_{m-1}^T] \\ &= [\beta_1, \beta_2, \dots, \beta_N] \\ \boldsymbol{\nu}^T &= [\sigma_1^2, \sigma_2^2, \dots, \sigma_{m-1}^2] \\ \boldsymbol{\alpha}^T &= [\alpha_1, \alpha_2, \dots, \alpha_{m-1}, \alpha_m] \\ \boldsymbol{\nu}^T &= [\nu_1, \nu_2, \dots, \nu_{m-1}, \nu_m] \\ &\text{be } \boldsymbol{\beta}^T \text{ without } \beta_i, \end{aligned}$$

where $N = p + \sum_{u=1}^{m-1} q_u = p + q$, and

$$\boldsymbol{\beta}_{-i}^T = [\beta_1, \beta_2, \dots, \beta_{i-1}, \beta_{i+1}, \dots, \beta_N].$$

And let

$$\boldsymbol{\nu}_{-u}^T = [\sigma_1^2, \sigma_2^2, \dots, \sigma_{u-1}^2, \sigma_{u+1}^2, \dots, \sigma_{m-1}^2]$$

be $\boldsymbol{\nu}^T$ without variance component u . Then the joint posterior density is in the normal-gamma form (Macedo and Gianola, 1987):

$$\begin{aligned} P(\boldsymbol{\beta}, \boldsymbol{\nu}, \sigma_m^2 | \mathbf{y}, \boldsymbol{\alpha}, \boldsymbol{\nu}) \propto & (\sigma_m^2)^{-(n+v_m+2)2} \exp\left\{-\frac{1}{2\sigma_m^2} \left[(\mathbf{y} - \mathbf{X}\mathbf{b} - \sum_{u=1}^{m-1} \mathbf{U}_u \mathbf{e}_u)^T \right. \right. \\ & \cdot \left. \left. (\mathbf{y} - \mathbf{X}\mathbf{b} - \sum_{u=1}^{m-1} \mathbf{U}_u \mathbf{e}_u) + v_m \alpha_m \right] \right\} \\ & \times \prod_{u=1}^{m-1} \left[(\sigma_u^2)^{-(q_u+v_u+2)2} \exp\left\{-\frac{1}{2\sigma_u^2} \left[\mathbf{e}_u^T \mathbf{R}_u^{-1} \mathbf{e}_u \right. \right. \right. \\ & \left. \left. \left. + v_u \alpha_u \right] \right\} \right] \quad (27) \end{aligned}$$

Inference about each of the unknowns ($\boldsymbol{\beta}, \boldsymbol{\nu}, \sigma_m^2$) are based on their marginal densities, respectively.

Gibbs sampling can be implemented for constructing the fully conditional posterior densities of all unknowns in (27).

The conditional posterior densities of each of the location parameters in $\boldsymbol{\beta}$ is normal, with mean $\tilde{\beta}_i$ and variance \tilde{s}_i^2 :

$$\boldsymbol{\beta}_i | \mathbf{y}, \boldsymbol{\beta}_{-i}, \boldsymbol{\nu}, \sigma_m^2, \boldsymbol{\alpha}, \boldsymbol{\nu} \sim N(\tilde{\beta}_i, \tilde{s}_i^2), \quad i = 1, 2, \dots, N \quad (28)$$

where $\tilde{\beta}_i = (d_i - \sum_{j=1, j \neq i}^N w_{ij} \beta_j) / w_{ii}$ and $\tilde{s}_i^2 = \sigma_m^2 / w_{ii}$, w_{ij} is the element of i th row and j th column of matrix \mathbf{W} in the left hand side of normal equations (12) and d_i is the i th element of vector \mathbf{d} in the right hand side of normal equation (12).

The conditional posterior density of residual variances σ_m^2 is in the scaled inverted chi-square form :

$$\Pr(\sigma_m^2 \mid \mathbf{y}, \boldsymbol{\beta}, \boldsymbol{\nu}, \boldsymbol{\alpha}, \boldsymbol{\nu}) \propto (\sigma_m^2)^{(n+v_m+2)} \exp\left\{-\frac{1}{2\sigma_m^2} \left[(\mathbf{y} - \mathbf{X}\mathbf{b} - \sum_{u=1}^{m-1} \mathbf{U}_u \mathbf{e}_u)^T \cdot (\mathbf{y} - \mathbf{X}\mathbf{b} - \sum_{u=1}^{m-1} \mathbf{U}_u \mathbf{e}_u) + v_m \alpha_m \right]\right\}$$

or

$$\sigma_m^2 \mid \mathbf{y}, \boldsymbol{\beta}, \boldsymbol{\nu}, \boldsymbol{\alpha}, \boldsymbol{\nu} \sim \frac{\tilde{v}_m \tilde{\alpha}_m}{\chi^2(df = \tilde{v}_m)} \quad (29)$$

with parameters $\tilde{v}_m = n + v_m$ and $\tilde{\alpha}_m = [(\mathbf{y} - \mathbf{X}\mathbf{b} - \sum_{u=1}^{m-1} \mathbf{U}_u \mathbf{e}_u)^T (\mathbf{y} - \mathbf{X}\mathbf{b} - \sum_{u=1}^{m-1} \mathbf{U}_u \mathbf{e}_u) + v_m \alpha_m] / \tilde{v}_m$

The conditional posterior density of the u th variance σ_u^2 is also in the scaled inverted chi-square form :

$$\Pr(\sigma_u^2 \mid \mathbf{y}, \boldsymbol{\beta}, \boldsymbol{\nu}_{-u}, \sigma_m^2, \boldsymbol{\alpha}, \boldsymbol{\nu}) \propto (\sigma_u^2)^{(q_u+v_u+2)} \exp\left\{-\frac{1}{2\sigma_u^2} [\mathbf{e}_u^T \mathbf{R}_u^{-1} \mathbf{e}_u + v_u \alpha_u]\right\}$$

or

$$\sigma_u^2 \mid \mathbf{y}, \boldsymbol{\beta}, \boldsymbol{\nu}_{-u}, \sigma_m^2, \boldsymbol{\alpha}, \boldsymbol{\nu} \sim \frac{\tilde{v}_u \tilde{\alpha}_u}{\chi^2(df = \tilde{v}_u)} \quad (30)$$

with parameters $\tilde{v}_u = q_u + v_u$ and $\tilde{\alpha}_u = [\mathbf{e}_u^T \mathbf{R}_u^{-1} \mathbf{e}_u + v_u \alpha_u] / \tilde{v}_u$.

A set of the $N + m$ conditional posterior distributions (28)–(30) is called the Gibbs sampler. Flat priors for all variance components $\Pr(\boldsymbol{\nu}, \sigma_m^2) \propto \text{constant}$ can be set for the Gibbs sampler. The degree of belief parameters can be set as $v_u = -2$ for $u = 1, 2, \dots, m$.

Bayesian inference can be obtained for the marginal distributions through Gibbs sampling (Gelfand and Smith, 1990). Generating random samples from the joint posterior distribution (27) can be achieved through successively drawing samples from and updating the Gibbs sampler (28)–(30).

Gibbs sampling works as follows :

A. set unbiased predictors and estimates as initial values for $\boldsymbol{\beta}, \boldsymbol{\nu}$ and σ_m^2 ;

B. generate β_i from (28) and update $\beta_i, i = 1, 2, \dots, N$;

C. generate σ_m^2 from (29) and update σ_m^2 ;

D. generate σ_u^2 from (30) and update $\sigma_u^2, u = 1, 2, \dots, m-1$;

Repeat B. – D. for k (length of the chain) times. As $k \rightarrow \infty$, this will create a Markov chain with equilibrium distribution. After running initial iterations as "warm-up", samples are stored every d iterations with the total number of samples saved to be s .

If the Gibbs sampler converges to the equilibrium distribution, the s samples are randomly drawn from the joint posterior distribution with density (27). The k th sample

$$\{\boldsymbol{\beta}_k, \boldsymbol{\nu}_k \text{ and } (\sigma_m^2)_i\}, k = 1, 2, \dots, s \quad (31)$$

is then an $N + m$ vector, each elements of which is a drawing from the appropriate marginal distribution. The s samples in (31) is called Gibbs samples for reference. The features of the posterior distribution $P(x)$ can be estimated by

$$\hat{c} = \frac{1}{s} \sum_{k=1}^s g(x_k)$$

where $g(x_k)$ can be any feature of $P(x)$, such as its mean or variance.

Bayesian inference can also be made on the functions of the original parameters.

GENETIC MODELS

Animal genetic models

Genotype \times environment (GE) interactions have been detected for quantitative traits of many plants and animals. With genetic experiments conducted in multiple environments, the average phenotypic performance of a genetic entry in one environment can be expressed by the following genetic model,

$$y = \mu + E + G + GE + \varepsilon \quad (32)$$

where μ = population mean, E = environment effect, G = total genotypic effect, GE = genotype \times environment interaction effect, ε = residual effect.

But most animal models (or reduced animal models) consist of only simple genetic effects, such as additive, dominance, and/or maternal effects (Lynch and Walsh, 1998). Recently Zhu and Weir (1996) proposed an animal model, which is a modification of Eisen's model

(Eisen et al. , 1966). The genetic model for the phenotypic mean (y_{ijsk}) of sex s in block k within environment h from the cross between maternal line i and paternal line j is

$$y_{hijks} = \mu + E_h + G_{ijs} + GE_{hij s} + B_{k(h)} + \varepsilon_{hijks} \quad (33)$$

where μ is the population mean , E_h is the environment effect , $B_{k(h)}$ is the block effect , $\varepsilon_{hijks} \sim (0, \sigma_e^2)$ is the residual effect. The total genotype effect is further partitioned into three components (G = additive effect A + dominance effect D + sex-linked effect L + maternal effect M), the same as in the partitioning of the genotype \times environment interaction effect ($GE = AE + DE + LE + ML$) for heterogametic progeny (XY or ZW , $s = 1$) and for homogametic progeny (XX or ZZ , $s = 2$) (Zhu and Weir , 1996) :

$$\begin{aligned} G_{ij1}^{XY} + GE_{hij1}^{XY} &= A_i + A_j + D_{ij} + L_{i1} + M_i \\ &+ AE_{hi} + AE_{hj} + DE_{hij} \\ &+ LE_{hi1} + ME_{hi} \\ \text{or } G_{ij1}^{ZW} + GE_{hij1}^{ZW} &= A_i + A_j + D_{ij} + L_{j1} \\ &+ M_i + AE_{hi} + AE_{hj} \\ &+ DE_{hij} + LE_{hj1} + ME_{hi} \\ G_{ij2}^{XX/ZZ} + GE_{hij2}^{XX/ZZ} &= A_i + A_j + D_{ij} + \frac{1}{2}L_{i2} \\ &+ \frac{1}{2}L_{j2} + M_i + AE_{hi} \\ &+ AE_{hj} + DE_{hij} + \frac{1}{2}LE_{hi2} \\ &+ \frac{1}{2}LE_{hj2} + ME_{hi} \quad (34) \end{aligned}$$

The phenotypic mean of this animal model with sex-linked and maternal effects can be expressed by a mixed linear model as

$$\begin{aligned} \mathbf{y} &= \mathbf{Xb} + \mathbf{U}_A \mathbf{e}_A + \mathbf{U}_D \mathbf{e}_D + \mathbf{U}_L \mathbf{e}_L + \mathbf{U}_M \mathbf{e}_M \\ &+ \mathbf{U}_{AE} \mathbf{e}_{AE} + \mathbf{U}_{DE} \mathbf{e}_{DE} + \mathbf{U}_{LE} \mathbf{e}_{LE} + \mathbf{U}_{ME} \mathbf{e}_{ME} \\ &+ \mathbf{U}_B \mathbf{e}_B + \mathbf{e}_\varepsilon \\ &= \mathbf{Xb} + \sum_u^{10} \mathbf{U}_u \mathbf{e}_u \quad (35) \end{aligned}$$

with variance-covariance matrix

$$\begin{aligned} \text{var}(\mathbf{y}) &= \sigma_A^2 \mathbf{U}_A \mathbf{U}_A^T + \sigma_D^2 \mathbf{U}_D \mathbf{U}_D^T + \sigma_L^2 \mathbf{U}_L \mathbf{U}_L^T \\ &+ \sigma_M^2 \mathbf{U}_M \mathbf{U}_M^T + \sigma_{AE}^2 \mathbf{U}_{AE} \mathbf{U}_{AE}^T \\ &+ \sigma_{DE}^2 \mathbf{U}_{DE} \mathbf{U}_{DE}^T + \sigma_{LE}^2 \mathbf{U}_{LE} \mathbf{U}_{LE}^T \end{aligned}$$

$$\begin{aligned} &+ \sigma_{ME}^2 \mathbf{U}_{ME} \mathbf{U}_{ME}^T + \sigma_B^2 \mathbf{U}_B \mathbf{U}_B^T + \sigma_\varepsilon^2 \mathbf{I} \\ &= \sum_{u=1}^{10} \sigma_u^2 \mathbf{V}_u \quad (36) \end{aligned}$$

Unbiased estimation of variances and covariances can be obtained by REML or MINQUE (1) approaches. Random effects can be predicted by the BLUP , LUP or AUP method. Mouse body weight and tail length of a 7×7 diallel cross were analyzed by this animal model (Zhu and Weir , 1996 ; Atchley and Zhu , 1997). Silkworm is a heterogametic female species with ZZ sex chromosomes for males and ZW sex chromosomes for females. Data for cocoon weight and fibroin content for a 5×5 diallel cross in two seasons were analyzed for evaluating genetic variance components as well as genotype \times environment interaction variance components (Zhu and Weir , 1996).

Seed genetic models

One of the important breeding goals now is improvement of crop quality. Creating seed genetic models in biological meaning with applicable statistical methods is of importance for efficient analysis of seed quantitative traits. By extending Cockerham's general genetic model (Cockerham , 1980) , Zhu and Weir (1994a) partitioned the total genotype effect (G) into seed direct gene effect (G_0) , cytoplasm gene effect (G_C) , and maternal nuclear gene effect (G_M) ($G = G_0 + G_C + G_M$). Further partitioning was also proposed :

$$\begin{aligned} G_0 &= \sum_i \tau_i A_i + \sum_i \sum_{j \geq i} \delta_{ij} D_{ij} \\ G_C &= \sum_i \gamma_i C_i \quad (37) \end{aligned}$$

$G_M = \sum_i \tau_{mi} A m_i + \sum_i \sum_{j \geq i} \delta_{mij} D m_{ij}$ where A_i = direct additive effect , D_{ij} = direct dominance effect , C_i = cytoplasm gene effect , $A m_i$ = maternal additive effect , $D m_{ij}$ = maternal dominance effect.

Genetic models were proposed for quantitative traits of diploid seeds and animals (Zhu and Weir , 1994a) and of triploid endosperm (Zhu and Weir , 1994b). Usually , means of only three generations (P 's , F_1 's and F_2 's) are required for analyzing seed traits.

The total genotype \times environment interac-

tion (GE) can also be partitioned into three terms ($GE = G_oE + G_cE + G_mE$) (Zhu , 1994) , which can be further partitioned into its components :

$$\begin{aligned} & \text{direct} \times \text{environment interaction } G_oE = \\ & \sum_h \sum_i \alpha_{hi} AE_{hi} + \sum_h \sum_i \sum_{j \geq i} \beta_{hij} DE_{hij} \\ & \text{cytoplasm} \times \text{environment interaction } G_cE \\ & = \sum_h \sum_i \lambda_{hi} CE_{hi} \end{aligned} \quad (38)$$

$$\begin{aligned} & \text{maternal} \times \text{environment interaction } G_mE = \\ & \sum_h \sum_i \alpha_{m_i} AmE_{hi} + \sum_h \sum_i \sum_{j \geq i} \beta_{m_{hij}} DmE_{hij} \end{aligned}$$

where $AE_{hi} = A_i \times E_h$ interaction effect , $DE_{hij} = D_{ij} \times E_h$ interaction effect , $AE_{hi} = A_i \times E_h$ interaction effect , $AmE_{hi} = Am_i \times E_h$ interaction effect , $DmE_{hij} = Dm_{ij} \times E_h$ interaction effect .

Based on the extension of the general genetic model for seeds , experiments of a diallel cross with three generations (P's , F₁'s and F₂'s) in multiple environments can be appropriately analyzed by the mixed linear approaches (Zhu , 1996). The phenotype mean of seed models can be expressed by a mixed linear model as

$$\begin{aligned} \mathbf{y} &= \mathbf{Xb} + \mathbf{U}_A \mathbf{e}_A + \mathbf{U}_D \mathbf{e}_D + \mathbf{U}_C \mathbf{e}_C + \mathbf{U}_{Am} \mathbf{e}_{Am} \\ &+ \mathbf{U}_{Dm} \mathbf{e}_{Dm} + \mathbf{U}_{AE} \mathbf{e}_{AE} + \mathbf{U}_{DE} \mathbf{e}_{DE} + \mathbf{U}_{CE} \mathbf{e}_{CE} \\ &+ \mathbf{U}_{AmE} \mathbf{e}_{AmE} + \mathbf{U}_{DmE} \mathbf{e}_{DmE} + \mathbf{U}_B \mathbf{e}_B + \mathbf{e}_\epsilon \\ &= \mathbf{Xb} + \sum_u^{12} \mathbf{U}_u \mathbf{e}_u \end{aligned} \quad (39)$$

with variance-covariance matrix

$$\begin{aligned} \text{va}(\mathbf{y}) &= \sigma_A^2 \mathbf{V}_1 + \sigma_D^2 \mathbf{V}_2 + \sigma_C^2 \mathbf{V}_3 + \sigma_{Am}^2 \mathbf{V}_4 \\ &+ \sigma_{Dm}^2 \mathbf{V}_5 + \sigma_{AE}^2 \mathbf{V}_6 + \sigma_{DE}^2 \mathbf{V}_7 + \sigma_{CE}^2 \mathbf{V}_8 \\ &+ \sigma_{AmE}^2 \mathbf{V}_9 + \sigma_{DmE}^2 \mathbf{V}_{10} + \sigma_B^2 \mathbf{V}_{11} \\ &+ \sigma_{A.Am} \mathbf{V}_{12} + \sigma_{D.Dm} \mathbf{V}_{13} + \sigma_{AE.AmE} \mathbf{V}_{14} \\ &+ \sigma_{DE.DmE} \mathbf{V}_{15} + \sigma_\epsilon^2 \mathbf{V}_{16} \\ &= \sum_{u=1}^{16} \theta_u \mathbf{V}_u \end{aligned}$$

where $\mathbf{V}_u = \mathbf{U}_u \mathbf{U}_u^T$ ($u = 1, 2, \dots, 11$) , $\mathbf{V}_{12} = (\mathbf{U}_1 \mathbf{U}_4^T + \mathbf{U}_4 \mathbf{U}_1^T)$, $\mathbf{V}_{13} = (\mathbf{U}_2 \mathbf{U}_5^T + \mathbf{U}_5 \mathbf{U}_2^T)$, $\mathbf{V}_{14} = (\mathbf{U}_6 \mathbf{U}_9^T + \mathbf{U}_9 \mathbf{U}_6^T)$, $\mathbf{V}_{15} = (\mathbf{U}_7 \mathbf{U}_{10}^T + \mathbf{U}_{10} \mathbf{U}_7^T)$, $\mathbf{V}_{16} = \mathbf{I}$.

Unbiased estimation of variances and covariances can be obtained by MINQUE (0/1) approaches. Random effects can be predicted by LUP or AUP method. Quantitative traits of seed

nutrition were studied by using the seed models for rice (Shi et al. 1997) , cotton (Zhu et al. , 1997) , barley (Yan X. F. , et al. , 1998) , and corn (Lou et al. , 1998).

QTL mapping models

Mixed linear model approaches were often used for mapping QTLs of animal populations based on animal model or reduced animal model (Grignola , et. al. , 1997) ,

$$\begin{aligned} \mathbf{y} &= \mathbf{Xb} + \mathbf{U}_A \mathbf{e}_A + \mathbf{U}_Q \mathbf{e}_Q + \mathbf{e}_\epsilon \\ &\sim \mathcal{N}(\mathbf{Xb}, \mathbf{V}) = \sigma_A^2 \mathbf{U}_A \mathbf{R}_A \mathbf{U}_A^T + \sigma_Q^2 \mathbf{U}_Q \mathbf{R}_Q \mathbf{U}_Q^T \\ &\quad + \sigma_\epsilon^2 \mathbf{R}_\epsilon \end{aligned} \quad (40)$$

where \mathbf{y} is the phenotype vector ; \mathbf{b} is a vector of fixed effects ; \mathbf{X} is the design/covariate matrix relating to \mathbf{b} ; $\mathbf{e}_A \sim \mathcal{N}(\mathbf{0}, \sigma_A^2 \mathbf{R}_A)$ is the vector of additive effects ; $\mathbf{e}_Q \sim \mathcal{N}(\mathbf{0}, \sigma_Q^2 \mathbf{R}_Q)$ is the vector of QTL allelic effects ; $\mathbf{e}_\epsilon \sim \mathcal{N}(\mathbf{0}, \sigma_\epsilon^2 \mathbf{R}_\epsilon)$ is the vector of residual effects .

Until now there is no appropriate animal model for analyzing QTLs with genetic main effects as well as GE interaction effects. The mixed linear model approaches can be used indirectly for searching QTLs with genetic main effects and QTL \times environment interaction effects (Zhu , 1998 ; 1999 ; Yan , et al. , 1998).

If QTL mapping experiments are conducted in several environments (years and/or locations) , the phenotype means of genetic entries can be fitted by linear model (32) with random effects for environment effects (E) , genotype effects (G) , genotype \times environment interaction effects (GE) , and residual errors. The matrix form of the mixed linear model is

$$\begin{aligned} \mathbf{y} &= \mathbf{I}_\mu + \mathbf{U}_E \mathbf{e}_E + \mathbf{U}_G \mathbf{e}_G + \mathbf{U}_{GE} \mathbf{e}_{GE} + \mathbf{e}_\epsilon \\ &\sim \mathcal{N}(\mathbf{I}_\mu, \mathbf{V}) = \sigma_E^2 \mathbf{U}_E \mathbf{U}_E^T + \sigma_G^2 \mathbf{U}_G \mathbf{U}_G^T \\ &\quad + \sigma_{GE}^2 \mathbf{U}_{GE} \mathbf{U}_{GE}^T + \sigma_\epsilon^2 \mathbf{I} \end{aligned} \quad (41)$$

The random effects \mathbf{E} , \mathbf{G} and \mathbf{GE} are predicted by the AUP method (Zhu , 1993 ; Zhu and Weir , 1996). and then used to predict main effect data $y_{jG} = \mu + G_j$ on the genotype j across environments , and genotype \times environment interaction data $y_{h(j)GE} = \mu + E_h + GE_{hj}$ on the genotype j in environment h , respectively .

The composite interval mapping (CIM) method (Zeng , 1994) is then applied to analyze the predicted \hat{y}_{jG} for searching QTLs with ge-

netic main effects ,

$$\hat{y}_{\chi(G)} = \beta_{\alpha(G)} + \beta_{\chi(G)}^* X_j^* + \sum_i \beta_{\chi(G)} X_{ij} + \epsilon_{\chi(G)} \quad (42)$$

where $\beta_{\alpha(G)}$ is the population mean , $\beta_{\chi(G)}^*$ is the QTL main effect ; X_j^* is the coefficient for QTL effect ; $\beta_{\chi(G)}$ is the main effect for the i -th marker ; X_{ij} is the coefficient for the i -th marker effect ; and $\epsilon_{\chi(G)}$ is the residual error of the j -th genotype .

The predicted $\hat{y}_{h\chi(GE)}$ are analyzed also by the CIM method (Zeng , 1994) for dissecting QTLs with QTL \times E interaction effects in the h -th environment ,

$$\hat{y}_{h\chi(GE)} = \beta_{\alpha(GE_h)} + \beta_{\chi(GE_h)}^* X_{hj}^* + \sum_i \beta_{\chi(GE_h)} X_{hij} + \epsilon_{\chi(GE_h)} \quad (43)$$

where $\beta_{\alpha(GE_h)}$ is the population mean of environment h , $\beta_{\chi(GE_h)}^*$ is the QTL \times E interaction effect of environment h with coefficient X_{hj}^* ; $\beta_{\chi(GE_h)}$ is the effect for the i -th marker \times environment h with coefficient X_{hij} ; and $\epsilon_{\chi(GE_h)}$ is the residual error of the j -th genotype in environment h .

Mixed-model-based composite interval mapping (MCIM) (Zhu and Weir , 1998 ; Zhu , 1998) can be applied to directly search QTLs with genetic main effects and QTL \times environment interaction effects (Zhu , 1998 ; 1999 ; Wang et al. , 1999). When experiments for QTL mapping are conducted in multiple environments , the phenotype value of the j -th genetic entry in environment h can be expressed by a mixed linear model ,

$$y_{hj} = \mu + ax_{A_j} + dx_{D_j} + u_{E_h} e_{E_h} + u_{AE_h} e_{AE_h} + u_{DE_h} e_{DE_h} + \sum_f u_{M_{jf}} e_{M_{jf}} + \sum_l u_{ME_{hl}} e_{ME_{hl}} + \epsilon_{hj} \quad (44)$$

where μ is the population mean ; a and d are the fixed additive and dominance effects of QTL , respectively ; x_{A_j} and x_{D_j} are coefficients for genetic main effects ; $e_{E_h} \sim N(0, \sigma_E^2)$ is the effect of environment h with coefficient u_{E_h} ; $e_{AE_h} \sim N(0, \sigma_{AE}^2)$ is the additive \times environment interac-

tion effect with coefficient $u_{AE_{hj}}$; $e_{DE_h} \sim N(0, \sigma_{DE}^2)$ is the dominance \times environment interaction effect with coefficient $u_{DE_{hj}}$; $e_{M_{jf}} \sim N(0, \sigma_M^2)$ is the marker main effect with coefficient $u_{M_{jf}}$; $e_{ME_{hl}} \sim N(0, \sigma_{ME}^2)$ is the marker \times environment interaction with coefficient $u_{ME_{hl}}$; $\epsilon_{hj} \sim N(0, \sigma_\epsilon^2)$ is the random residual effects .

This model (44) can be expressed in matrix form ,

$$\begin{aligned} \mathbf{y} &= \mathbf{X}\mathbf{b} + \mathbf{U}_E \mathbf{e}_E + \mathbf{U}_{AE} \mathbf{e}_{AE} + \mathbf{U}_{DE} \mathbf{e}_{DE} + \mathbf{U}_M \mathbf{e}_M \\ &\quad + \mathbf{U}_{ME} \mathbf{e}_{ME} + \mathbf{e}_\epsilon \\ &= \mathbf{X}\mathbf{b} + \sum_{u=1}^6 \mathbf{U}_u \mathbf{e}_u \\ &\sim N(\mathbf{X}\mathbf{b}, \mathbf{V}) = \sum_{u=1}^6 \sigma_u^2 \mathbf{U}_u \mathbf{R}_u \mathbf{U}_u^T. \end{aligned} \quad (45)$$

where \mathbf{y} is the phenotype vector ; \mathbf{b} is the fixed parameter vector for population mean and QTL effects ; \mathbf{X} is the known incidence matrix of the fixed parameters ; $\mathbf{e}_1 = \mathbf{e}_E \sim N(0, \sigma_E^2 \mathbf{I})$ is the vector of environment effects ; $\mathbf{e}_2 = \mathbf{e}_{AE} \sim N(0, \sigma_{AE}^2 \mathbf{I})$ is the vector of $A \times E$ interaction effects ; $\mathbf{e}_3 = \mathbf{e}_{DE} \sim N(0, \sigma_{DE}^2 \mathbf{I})$ is the vector of $D \times E$ interaction effects ; $\mathbf{e}_4 = \mathbf{e}_M \sim N(\mathbf{0}, \sigma_M^2 \mathbf{R}_M)$ is the vector of marker main effects ; $\mathbf{e}_5 = \mathbf{e}_{ME} \sim N(\mathbf{0}, \sigma_{ME}^2 \mathbf{R}_{ME})$ is the vector of $M \times E$ interaction effects ; $\mathbf{e}_6 = \mathbf{e}_\epsilon \sim N(\mathbf{0}, \sigma_\epsilon^2 \mathbf{I})$ is the vector of residual effects ; \mathbf{U}_u ($u = 1, 2, \dots, 6$) are the known incidence matrix of the random effects and $\mathbf{U}_6 = \mathbf{I}$.

QTLs with epistasis main effects and epistasis \times environment interaction effects can also be analyzed by the MCIM method (Zhu , 1998 ; 1999). If DH or RIL populations are used for mapping QTLs with additive and additive \times additive epistasis effects as well as their environment interaction effects , the phenotype value of the j -th genetic entry in environment h can be expressed as the following mixed linear model ,

$$\begin{aligned} y_{hj} &= \mu + a_1 x_{A_{1j}} + a_2 x_{A_{2j}} + aax_{AA_j} + u_{E_h} e_{E_h} \\ &\quad + u_{A_1 E_{hj}} e_{A_1 E_h} + u_{A_2 E_{hj}} e_{A_2 E_h} \\ &\quad + u_{AAE_{hj}} e_{AAE_h} + \sum_f u_{M_{jf}} e_{M_{jf}} + \sum_l u_{MM_{lj}} e_{MM_l} \\ &\quad + \sum_p u_{ME_{hp}} e_{ME_{hp}} + \sum_q u_{MME_{hjq}} e_{MME_{hjq}} + \epsilon_{hj} \end{aligned} \quad (46)$$

where μ is the population mean ; a_1 and a_2 are the additive effects of loci Q_1 and Q_2 , respectively ; aa is the additive \times additive epistasis effect of loci Q_1 and Q_2 ; $x_{A_{1j}}$, $x_{A_{2j}}$ and x_{AA_j} are coefficients of these genetic main effects ; e_{E_h} are the random effects of environment h with coefficient $u_{E_{hj}}$; $e_{A_1E_h}$ (or $e_{A_2E_h}$) are the additive \times environment interaction effects with coefficient $u_{A_1E_{hj}}$ (or $u_{A_2E_{hj}}$) for Q_1 (or Q_2) ; e_{AAE_h} is the epistasis \times environment interaction effect with coefficient $u_{AAE_{hj}}$; e_{M_j} is the marker main effect with coefficient u_{M_j} ; e_{MM_i} is the marker \times marker interaction effect with coefficient u_{MM_i} ; $e_{ME_{hp}}$ is the marker \times environment interaction effect with coefficient $u_{ME_{hp}}$; $e_{MME_{hj}}$ is the marker \times marker \times environment interaction effect with coefficient $u_{MME_{phj}}$; ε_{hj} is the residual effect .

This model (46) can be expressed in matrix form ,

$$\begin{aligned} \mathbf{y} &= \mathbf{X}\mathbf{b} + \mathbf{U}_E\mathbf{e}_E + \mathbf{U}_{A_1E}\mathbf{e}_{A_1E} + \mathbf{U}_{A_2E}\mathbf{e}_{A_2E} \\ &+ \mathbf{U}_{AAE}\mathbf{e}_{AAE} + \mathbf{U}_M\mathbf{e}_M + \mathbf{U}_{MM}\mathbf{e}_{MM} \\ &+ \mathbf{U}_{ME}\mathbf{e}_{ME} + \mathbf{U}_{MME}\mathbf{e}_{MME} + \mathbf{e}_\varepsilon \\ &= \mathbf{X}\mathbf{b} + \sum_{u=1}^9 \mathbf{U}_u\mathbf{e}_u \\ &\sim \mathcal{N}(\mathbf{X}\mathbf{b}, \mathbf{V} = \sum_{u=1}^9 \sigma_u^2 \mathbf{U}_u \mathbf{R}_u \mathbf{U}_u^T). \end{aligned} \quad (47)$$

where \mathbf{y} is the phenotype vector ; \mathbf{b} is the fixed parameter vector for population mean and QTL effects ; \mathbf{X} is the known incidence matrix of the fixed parameters ; $\mathbf{e}_1 = \mathbf{e}_E \sim \mathcal{N}(\mathbf{O}, \sigma_E^2 \mathbf{I})$ is the vector of environment effects ; $\mathbf{e}_2 = \mathbf{e}_{A_1E} \sim \mathcal{N}(\mathbf{O}, \sigma_{A_1E}^2 \mathbf{I})$ is the vector of $A_1 \times E$ interaction effects ; $\mathbf{e}_3 = \mathbf{e}_{A_2E} \sim \mathcal{N}(\mathbf{O}, \sigma_{A_2E}^2 \mathbf{I})$ is the vector of $A_2 \times E$ interaction effects ; $\mathbf{e}_4 = \mathbf{e}_{AAE} \sim \mathcal{N}(\mathbf{O}, \sigma_{AAE}^2 \mathbf{R}_{AAE})$ is the vector of $AA \times E$ interaction effects ; $\mathbf{e}_5 = \mathbf{e}_M \sim \mathcal{N}(\mathbf{O}, \sigma_M^2 \mathbf{R}_M)$ is the vector of marker main effects ; $\mathbf{e}_6 = \mathbf{e}_{MM} \sim \mathcal{N}(\mathbf{O}, \sigma_{MM}^2 \mathbf{R}_{MM})$ is the vector of interaction marker main effects ; $\mathbf{e}_7 = \mathbf{e}_{ME} \sim \mathcal{N}(\mathbf{O}, \sigma_{ME}^2 \mathbf{R}_{ME})$ is the vector of $M \times E$ interaction effects ; $\mathbf{e}_8 = \mathbf{e}_{MME} \sim \mathcal{N}(\mathbf{O}, \sigma_{MME}^2 \mathbf{R}_{MME})$ is the vector of $MM \times E$ interaction effects ; $\mathbf{e}_9 = \mathbf{e}_\varepsilon \sim \mathcal{N}(\mathbf{O}, \sigma_\varepsilon^2 \mathbf{I})$ is the vector of residual effects ; \mathbf{U}_u ($u = 1, 2, \dots, 8$)

are the known incidence matrix of the random effects and $\mathbf{U}_9 = \mathbf{I}$.

DISCUSSION

Complex quantitative traits consist of genetic effects more than simple additive and dominance effects . As genetic models become more and more complicated for fitting the biological situations , total phenotypic variance can be partitioned into various ways . Therefore some definitions of traditional quantitative parameters might need to be updated too .

Heritability is an important parameter widely used in quantitative genetics as well as plant and animal breeding , but different definitions should be assigned in dissimilar genetic models . Quantitative traits can be controlled by genetic main effects and GE interaction effects . Accordingly , the total heritability (h^2) can be partitioned into general heritability (h_G^2) and interaction heritability (h_{GE}^2) (Zhu , 1997) . General heritability , which is applicable to multiple environments , is defined as the ratio of variances of accumulated inheritable genotypic effects to phenotypic variance . Interaction heritability , which is only applicable to specific environments , is defined as the ratio of variances of accumulated inheritable GE interaction effects to phenotypic variance . In seed genetic models , variances with accumulated effects consist of direct additive variance (V_A) , cytoplasm variance (V_C) , maternal additive variance (V_{Am}) as well as variances due to gene by environment interactions . General heritability consists of direct general heritability (h_G^2) , cytoplasm general heritability (h_C^2) , and maternal general heritability (h_M^2) (Zhu , 1996) :

$$\begin{aligned} h_G^2 &= h_0^2 + h_C^2 + h_M^2 \\ &= (V_A + C_{A.Am}) \mathcal{Y} V_p + V_c / V_p + (V_{Am} \\ &\quad + C_{A.Am}) \mathcal{Y} V_p \end{aligned}$$

Interaction heritability includes direct interaction heritability (h_{OE}^2) , cytoplasm interaction heritability (h_{CE}^2) , and maternal interaction heritability (h_{ME}^2) :

$$\begin{aligned} h_{GE}^2 &= h_{OE}^2 + h_{CE}^2 + h_{ME}^2 \\ &= (V_{AE} + C_{AE.AmE}) \mathcal{Y} V_p + V_{CE} / V_p + (V_{AmE} \end{aligned}$$

$$+ C_{AE.AmE}) V_p$$

with total phenotypic variance calculated as

$$\begin{aligned} V_p &= (V_{Go} + V_C + V_{Gm} + 2C_{Go.Gm}) + (V_{GoE} \\ &+ V_{CE} + V_{GmE} + 2C_{GoE.GmE}) + V_e \\ &= (V_A + V_D + V_C + V_{Am} + V_{Dm} \\ &+ 2C_{A.Am} + 2C_{D.Dm}) + (V_{AE} + V_{DE} \\ &+ V_{CE} + V_{AmE} + 2C_{AE.AmE} + 2C_{DE.DmE}) \\ &+ V_e \end{aligned}$$

Heritability is often used in predicting selection response. Since heritability consists of several components for some complicated models, the definition for selection response should also be changed. For seed models with *GE* interaction, total selection response ($R = ih^2 \sqrt{V_p}$) can be partitioned into several components (Zhu, 1997):

$$\begin{aligned} R &= R_G + R_{CE} \\ &= (R_O + R_C + R_M) + (R_{OE} + R_{CE} + R_{ME}) \end{aligned}$$

where $R_G = ih_G^2 \sqrt{V_p}$ is general response, which consists of direct general response ($R_O = ih_O^2 \sqrt{V_p}$), cytoplasm general response ($R_C = ih_C^2 \sqrt{V_p}$), and maternal general response ($R_M = ih_M^2 \sqrt{V_p}$); ($R_{CE} = ih_{GE}^2 \sqrt{V_p}$) is interaction response, which consists of direct interaction response ($R_{OE} = ih_{OE}^2 \sqrt{V_p}$), cytoplasm interaction response ($R_{CE} = ih_{CE}^2 \sqrt{V_p}$), and maternal interaction response ($R_{ME} = ih_{ME}^2 \sqrt{V_p}$).

In order to analyze complicated genetic effects (such as epistasis effects, endosperm effects, etc.), segregating generations of (F_2 , BC1, and BC2) can be included in the genetic models, which have non-integer coefficients for some effects and even correlation between factors. These kinds of genetic models are usually analyzable not by ANOVA approaches but by mixed linear model approaches. Most animal geneticists use the REML method (Patterson and Thompson, 1971) instead of MINQUE method (Rao, 1971) for analyzing animal models. Monte Carlo simulations (Zhu, 1989; Zhu and Weir, 1994a, 1994b, 1996) showed that MINQUE has advantages over REML due to its [A] simple computation without iterations, [B] no requirement for normality distribution, and [C]

unbiased estimation.

The jackknife resampling method is efficient for calculating estimates (or predictors) and their standard errors. Resampling technique is based on resampling unit. For genetic experiments with randomized complete block design in multiple environments, blocks within environments can serve as resampling units. If there are only replications but not blocks, genetic entries can serve as resampling units.

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